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SCIENCES

Emory College of Arts and Sciences Honors Program
Department of Data and Decision Sciences

Causal Representation Learning under Informative Missingness for Clinical Multimodal Prediction and Offline Decision-Making



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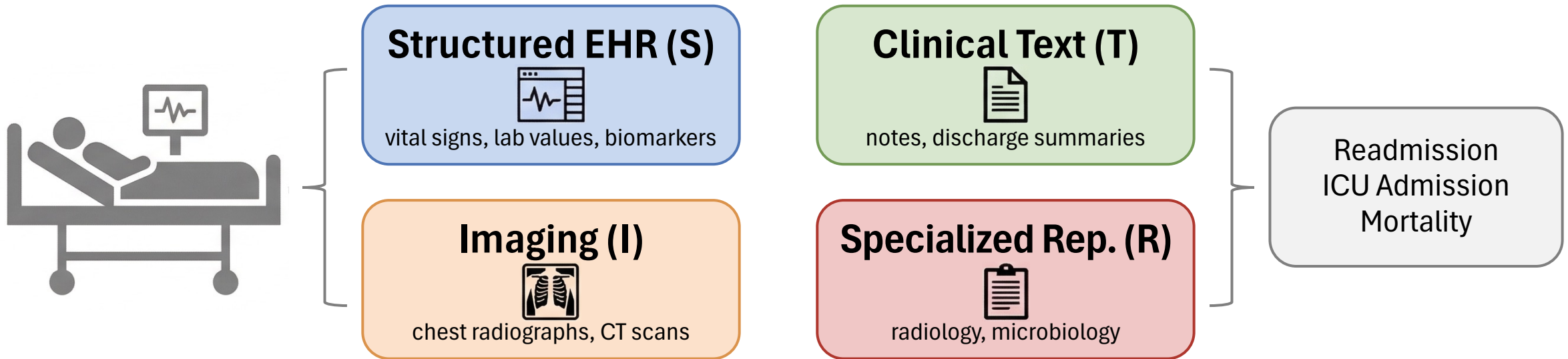
Thesis Committee: Prof. Ali Emami, Prof. Manuela Manetta

Big Picture & Motivation

From clinical observations to a modeling challenge

Promise: AI Meets the Modern Hospital

A hospitalized patient generates data from multiple streams simultaneously.



Each modality encodes a **different view** of the patient's physiological state and disease trajectory.

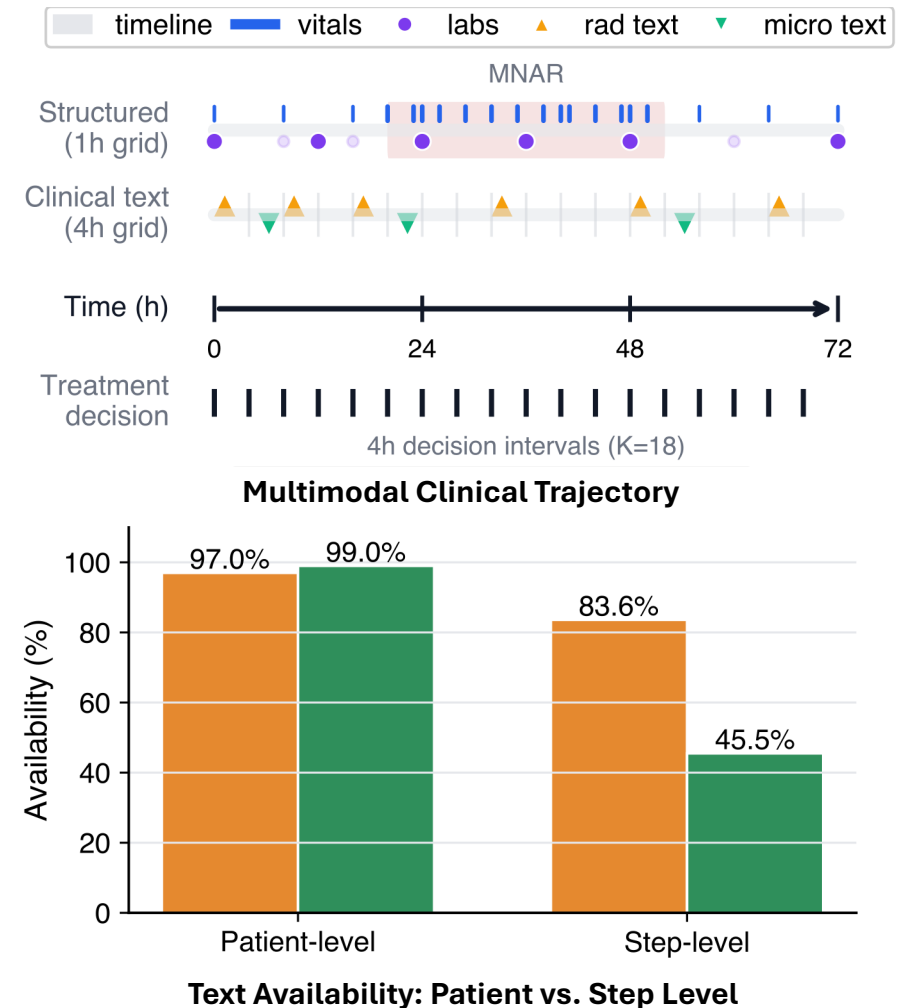
If AI can integrate these streams → Predict 30-day readmission · ICU admission · In-hospital mortality · Guide treatment decisions

Reality: Clinical Data Is Systematically Incomplete

- ✓ Structured vitals & labs → recorded on a 1-hour grid
- ✓ Clinical text (notes, summaries) → sparse, on a 4-hour decision grid
- ✓ In MIMIC-IV: 24.5% of hospitalized patients have no discharge summary
- ✓ Microbiology reports available at only 45.5% of ICU decision steps
- ✓ Text coverage: 97–99% at the patient level, but only 45.5–83.6% at the step level

These gaps are not random artifacts of data collection. They reflect deliberate clinical decisions.

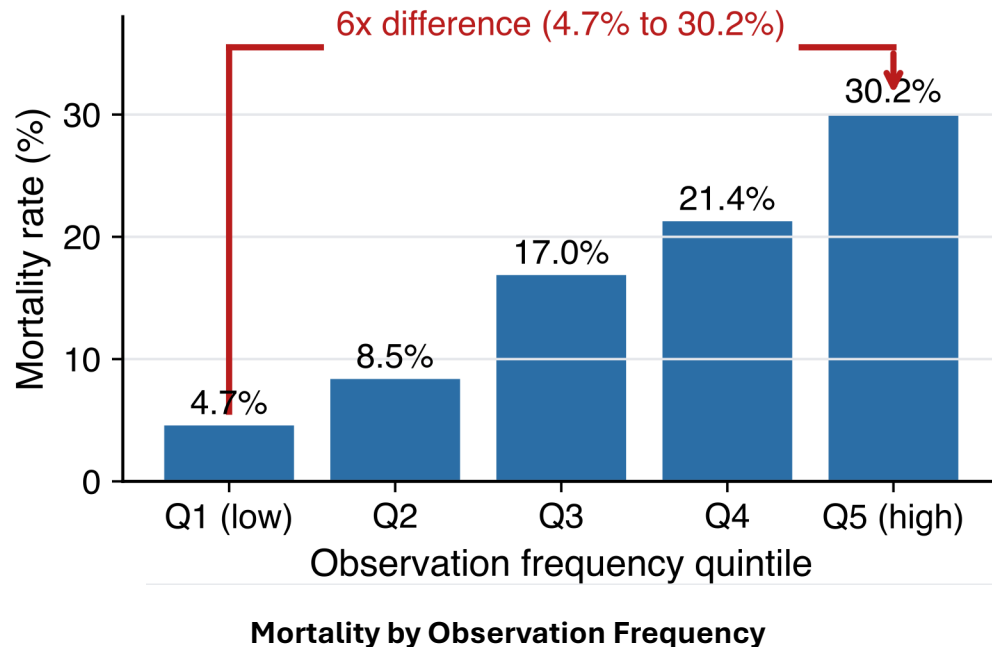
The data was not lost — it was never collected.



The Key Intuition: Absence Is a Signal

A concrete example:

A clinician orders a lactate measurement when **sepsis is suspected** — but not for patients who appear hemodynamically stable. The decision to observe depends on the very quantity the measurement would characterize.



This is **Missing Not At Random (MNAR)**: the probability of observing a value depends on the value itself.

~6× difference. Sicker patients are monitored more intensively.

"How patients are observed is at least as informative as what is observed in many clinical scenarios."

Where the Literature Falls Short

Area	Best existing work	Limitation
Multimodal fusion	SMIL, MUSE+, DrFuse	Assume MAR; don't model <i>why</i> data is missing
Temporal EHR models	GRU-D, BRITS, Raindrop	Step-level only; no cross-scale unification
Clinical RL	AI Clinician, CQL	Don't address MNAR in state learning
Causal missing data	Standard MNAR methods	No connection to policy learning or multimodal fusion

Four gaps this thesis addresses:

- Gap 1: Static vs. temporal missingness — never unified
- Gap 2: Observation process ($\delta \rightarrow y$) — causally unmodeled
- Gap 3: Prediction and decision-making under MNAR — developed independently
- Gap 4: No systematic diagnostic framework for MNAR failure types

The Core Problem: Informative Missingness

From missing data to informative observation processes

Why Standard Approaches Fail under MNAR

Standard missing data methods treat missingness as **noise to remove** — not signal to model.

Missing = Signal

observation pattern carries information

Patient ID	Date	Heart Rate	Blood Pressure	Lab Result
303101	21-03-25			B.0
302002	21-03-26	84		A.4
302003	21-03-27		190	B.3
203104	21-03-25	86		B.0
303105	21-03-25	70		B.4
302006	21-03-26		120	A.3

Illustrative example

Mean Imputation
fill with averages

wrong method
Loses pattern info

Complete-Case Analysis
drop incomplete records

wrong method
Selection Bias

Multiple Imputation
sample from assumed model

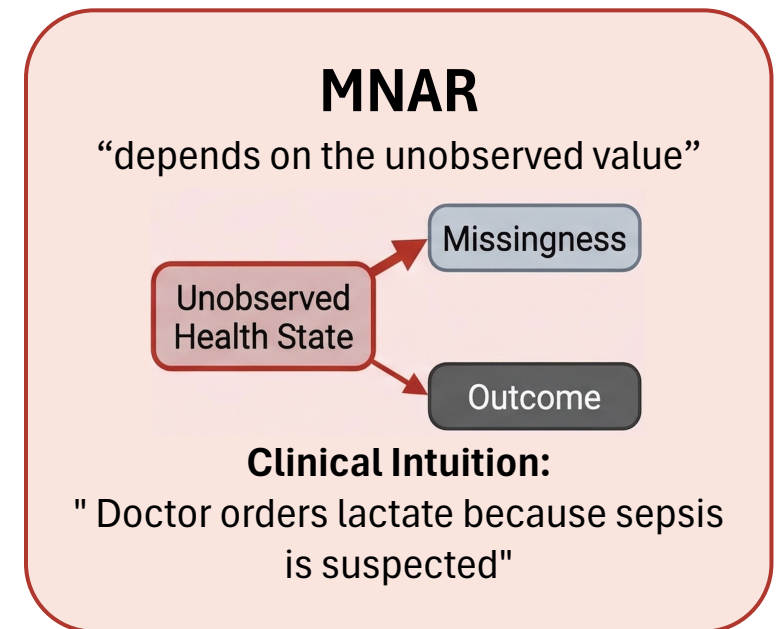
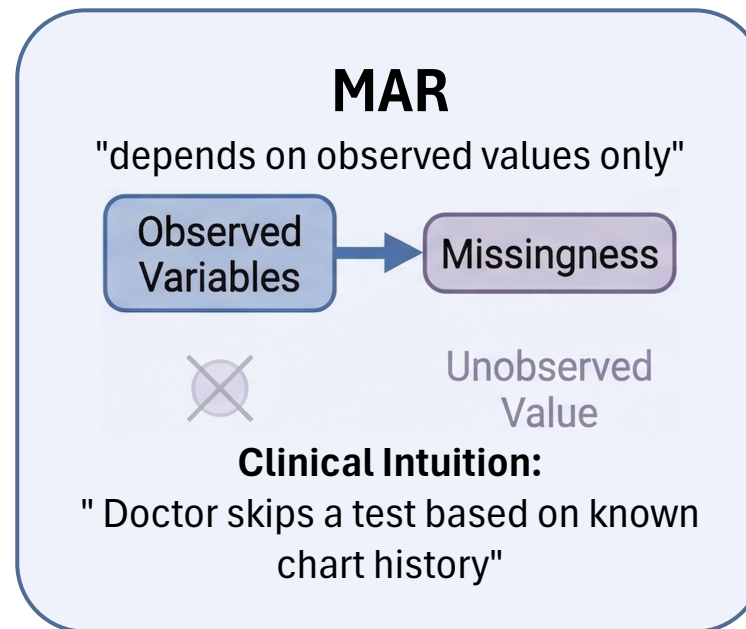
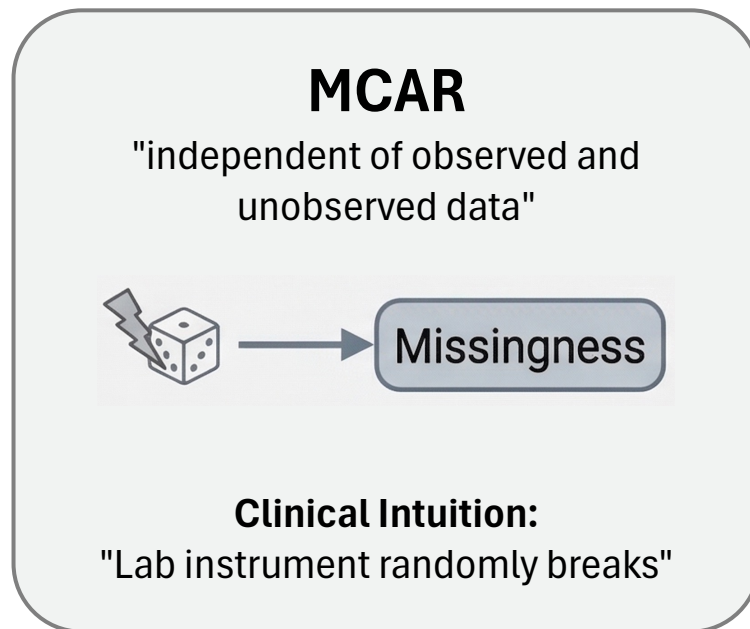
wrong method
Assumes MAR

MNAR-aware Modeling
Treat δ as a **causal variable**
Model observation patterns explicitly

MCAR, MAR, and MNAR:

Why the Distinction Matters

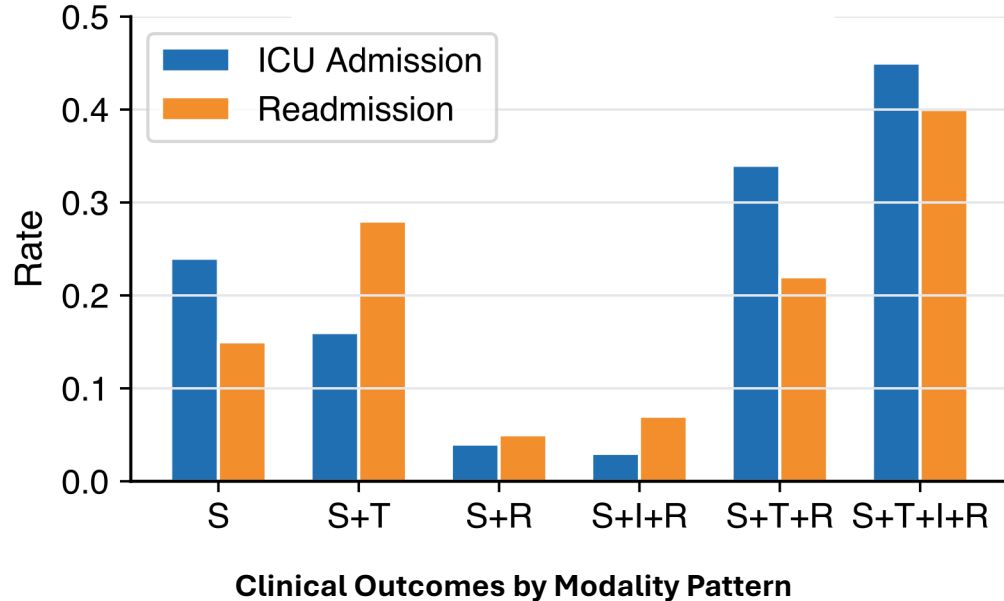
Three mechanisms by which data may be missing.



Clinical missingness is predominantly MNAR.

Key implication: The observation process correlates with the underlying clinical state — making it a *signal*, not noise.

Evidence: Which Tests Were Run Predicts What Happens Next



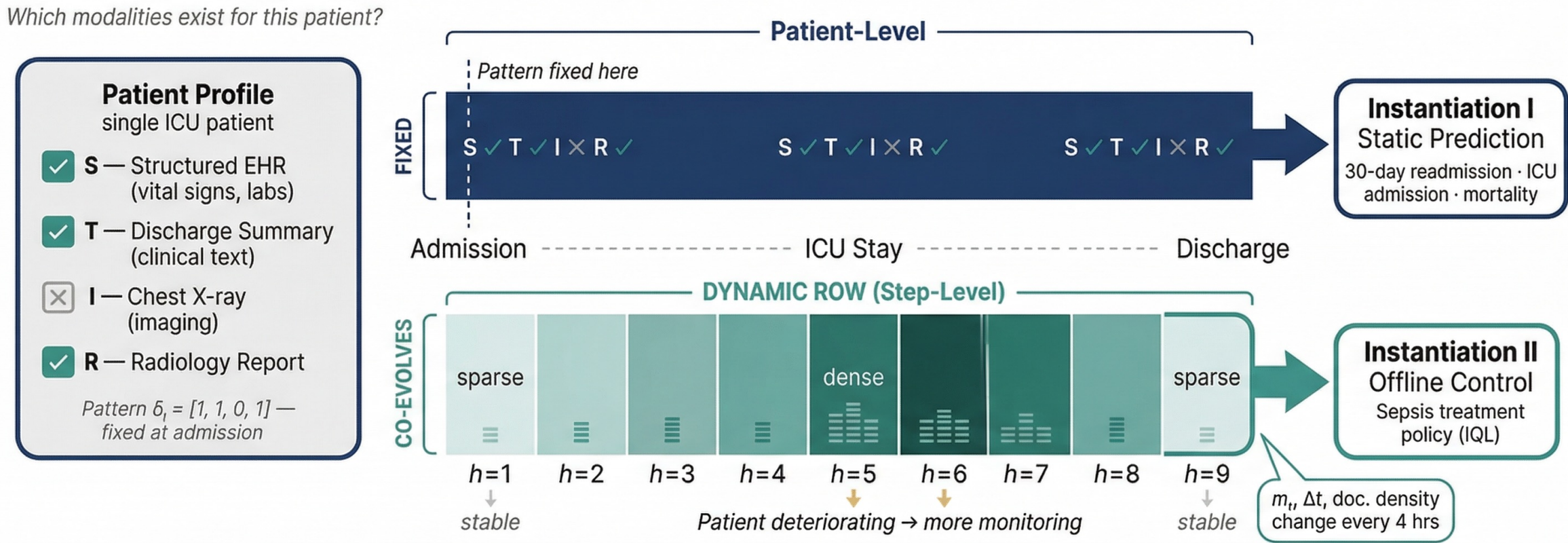
Patients with **complete multimodal records (S+I+T+R)** have **substantially higher** rates of ICU admission and 30-day readmission than those with only structured data (S only).

Conclusion:

Which tests a clinician chose to run is itself a predictor of outcome — independent of the test results.

Missingness Operates at Two Distinct Scales

This thesis identifies two complementary scales of informative missingness in clinical data:



My Thesis Question and Overall Framework

From problem formulation to a unified modeling framework

The Thesis Question

"How should observation patterns in multimodal clinical data — at both patient and step levels — be modeled to learn representations that are sufficient for prediction and control, and what methodological interventions correct the distinct failure modes that arise when such patterns are ignored?"

In plain language:

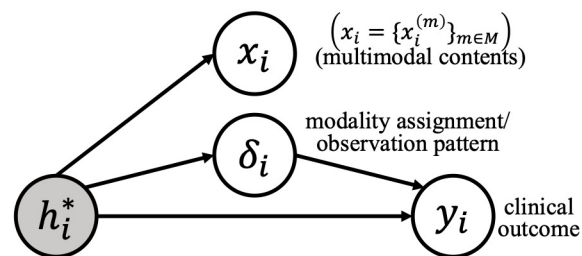
- **Q1 (Modeling):** How do we treat *who was tested, and how often* as signal — not noise?
- **Q2 (Correction):** When we ignore this, what breaks — and how do we fix it?

Three verifiable objectives:

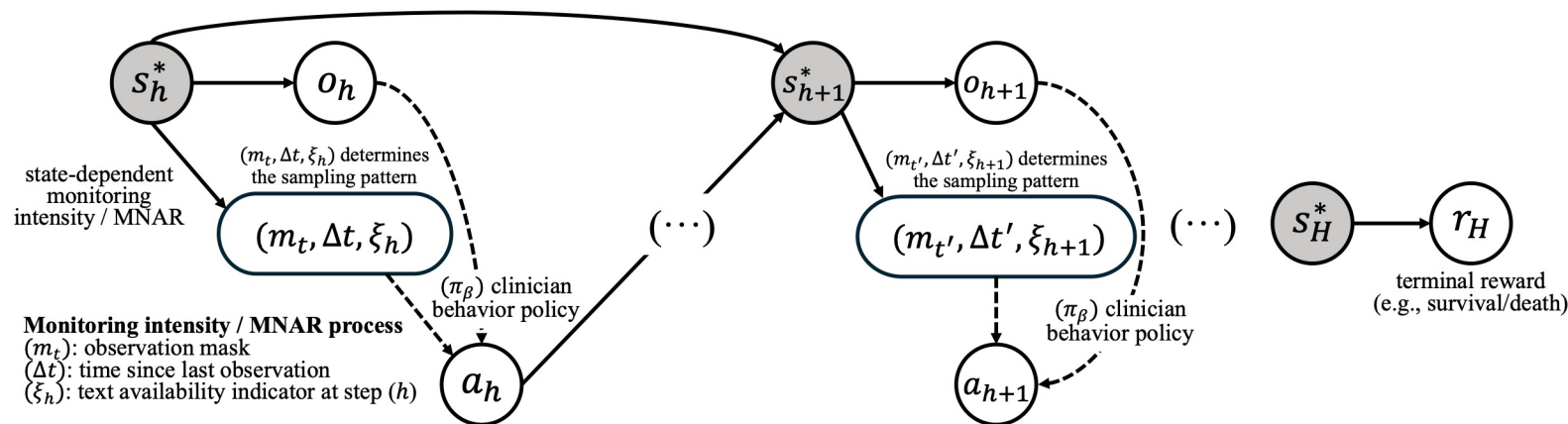
- **O1** — Representation sufficiency under MNAR
- **O2** — Observation process as explicit causal signal
- **O3** — Unified error decomposition & diagnostics

The Unified Causal Framework

Static Setting (patient-level modality missingness)



(a) Static setting (patient-level modality missingness)



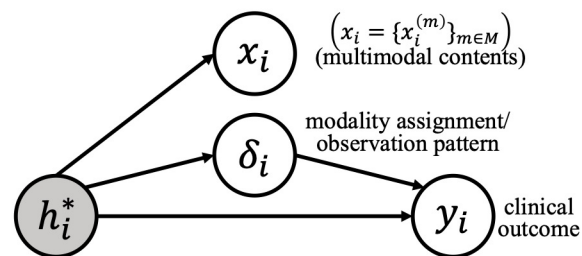
(b) Dynamic setting (step-level monitoring intensity variation)

The Unified Causal Framework

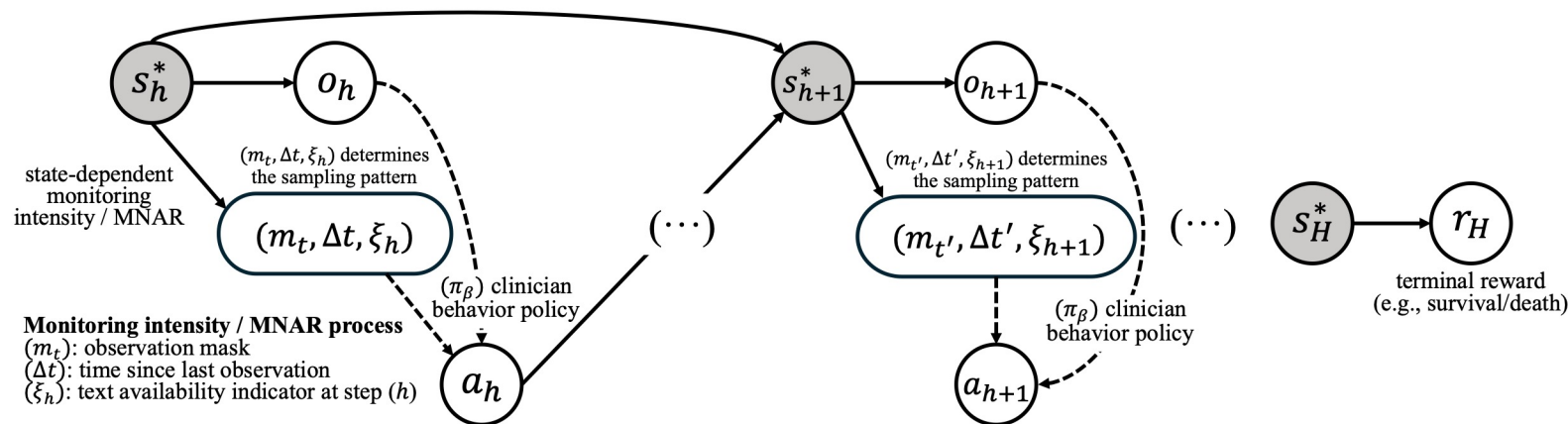
- Latent health $h_i^* \rightarrow$ multimodal contents x_i (what data is generated)
- Latent health $h_i^* \rightarrow$ observation pattern δ_i (which modalities the clinician ordered)
- Latent health $h_i^* \rightarrow$ clinical outcome y_i (the standard path)
- Critical extra edge: $\delta_i \rightarrow y_i$ directly (more tests $\rightarrow$ earlier intervention $\rightarrow$ changed outcome)

The Unified Causal Framework

Dynamic Setting (step-level monitoring intensity)



(a) Static setting (patient-level modality missingness)



(b) Dynamic setting (step-level monitoring intensity variation)

The Unified Causal Framework

- Latent state $s_h^* \rightarrow$ observations o_h and monitoring intensity $(m_t, \Delta t, \xi_h)$
- $(s_h^*, a_h) \rightarrow s_{h+1}^*$ (treatment changes the patient's state)
- Terminal state $s_H^* \rightarrow$ reward r_H (survival or death)

Overall, we treat observation process variables as first-class modeling objects, not nuisance factors to be imputed away.

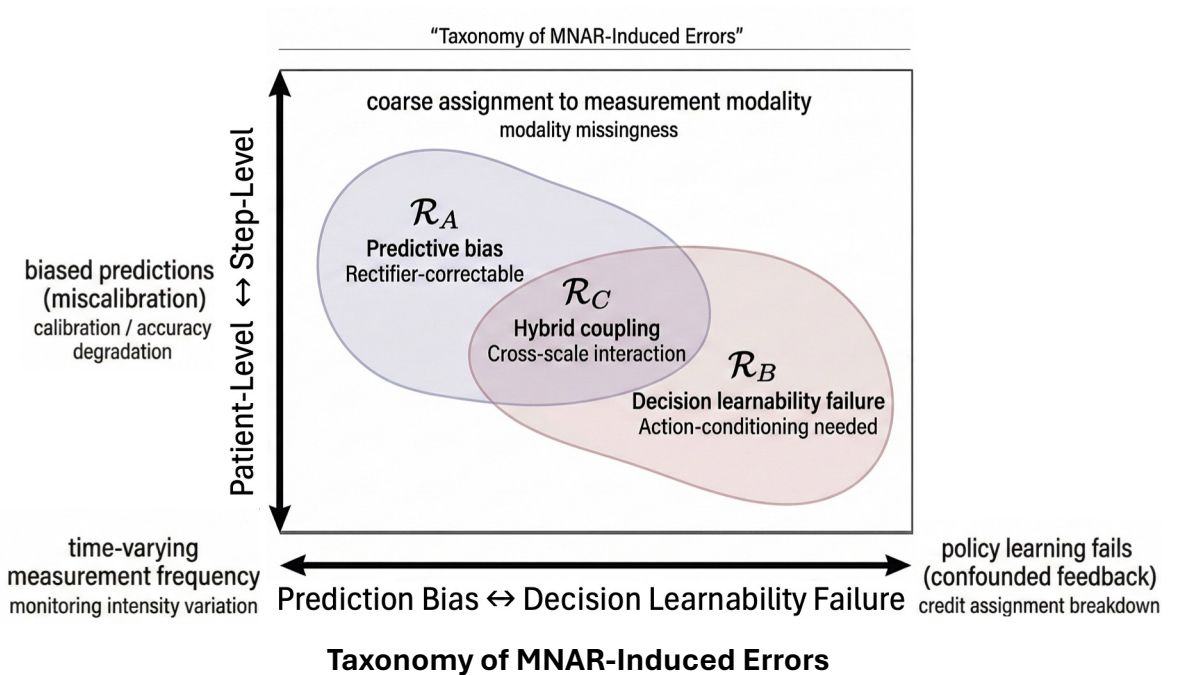
Two Tasks, Two Different Requirements

	Prediction	Decision-Making
Goal	Estimate outcome probability	Optimize treatment policy
Representation need	Prediction-sufficient: $Y \perp X \mid h$	Control-sufficient: state must encode how actions shape future states
MNAR failure mode	Pattern-specific calibration error	Credit assignment breakdown
Key Challenge	Residual bias even after good representation	Policy gradient cannot reach early actions

A representation that is prediction-sufficient may fail to be control-sufficient.

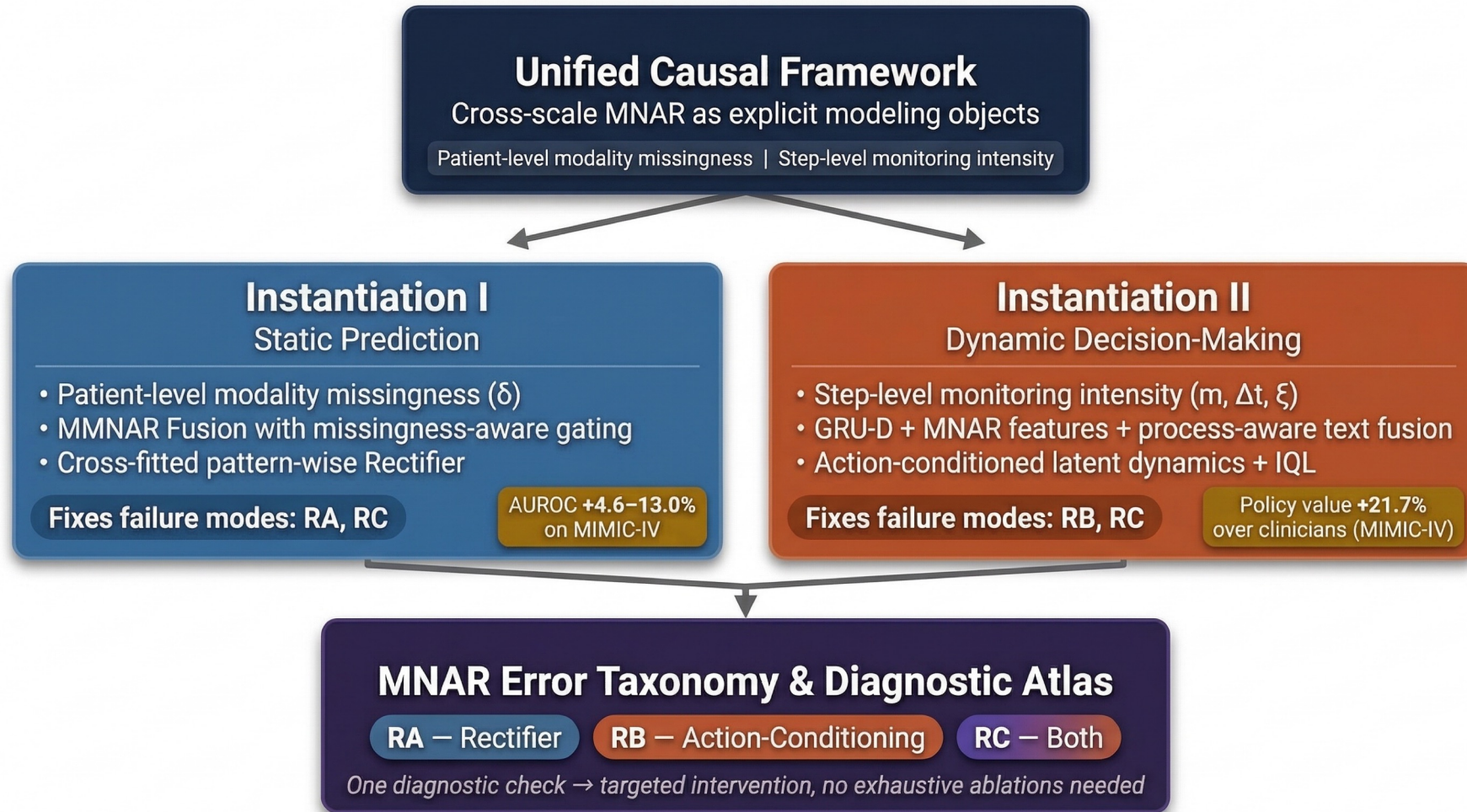
Three Ways MNAR Can Break Your Model

Regime	What breaks	Diagnostic signal	Fix
R_A — Predictive Bias	Miscalibrated predictions	Elevated ECE per pattern	Rectifier
R_B — Decision Learnability Failure	Policy fails; prediction looks fine	Near-zero ActSens	Action-conditioned dynamics
R_C — Hybrid	Both degrade	Elevated ECE + high Δ dissoc	both



Why this taxonomy matters: One diagnostic check before deployment tells you which fix to apply — no exhaustive ablations needed.

The Roadmap: One Framework, Two Paths



Two Instantiations: Prediction and Decision-Making

From representation learning to prediction and decision-making

Instantiation I: Static Prediction under Patient-Level Modality Missingness

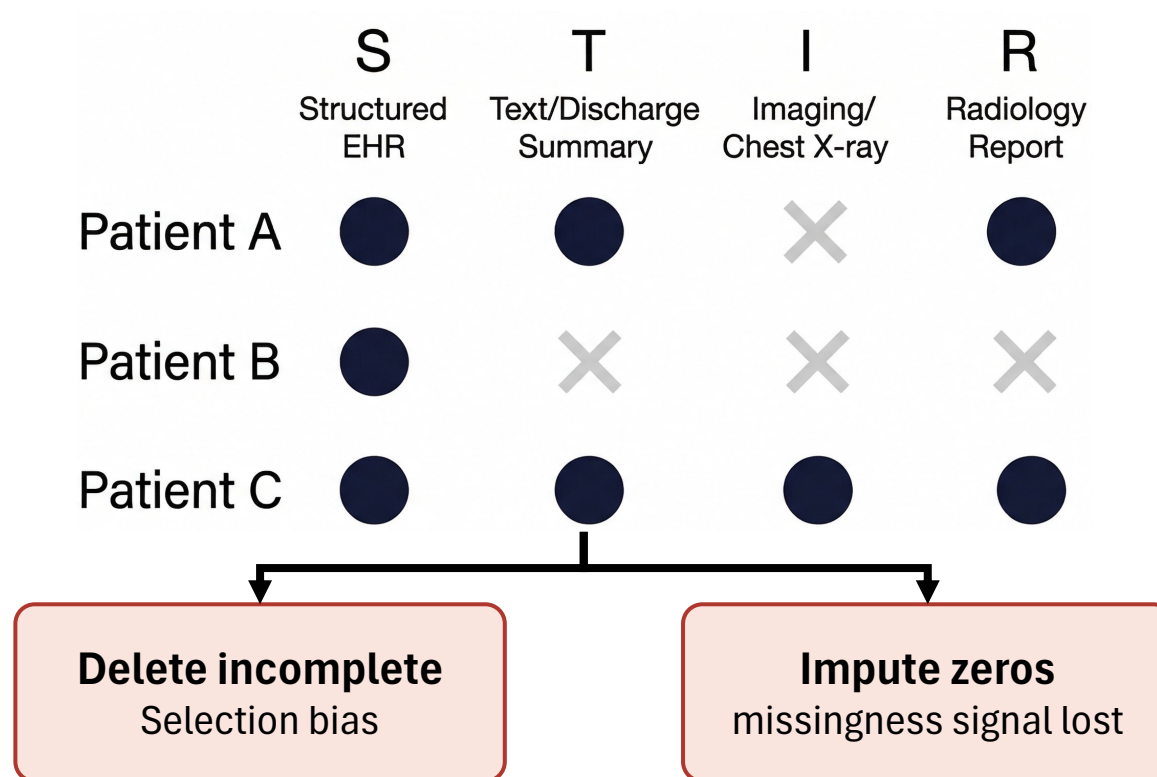
Setting: Episode-level prediction from multimodal ICU records — modality availability varies across patients.

Four modalities:

- S — Structured EHR (labs, vitals, demographics) · always present
- T — Discharge summaries · 75.5% of patients
- I — Chest X-rays · 26.1% of patients
- R — Radiology reports · 85.0% of patients

Three prediction targets (binary classification):

- 30-day unplanned hospital readmission
- Post-discharge ICU admission (within 90 days)
- In-hospital mortality



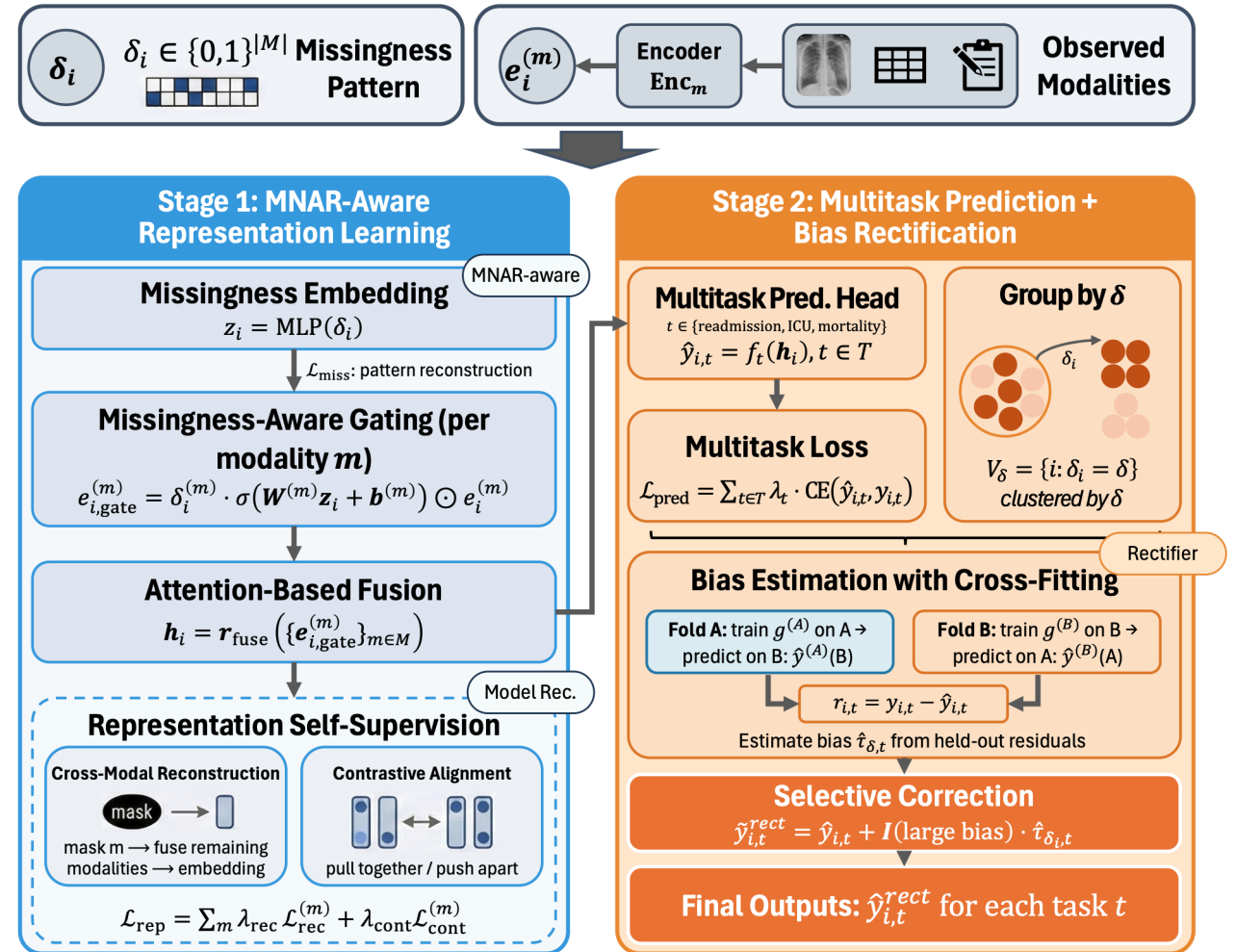
Instantiation I: Two-Stage MMNAR Pipeline

Stage 1 — Learn a Missingness-Aware Representation

- Encode who is missing (δ_i) as an explicit feature vector — not a hole to fill
- Gate each modality's contribution by the overall missingness pattern
- Self-supervision: reconstruct each modality from the others — forces the representation to be informationally complete

Stage 2 — Predict & Correct

- Predict all three outcomes from the shared representation h_i
- Rectifier: estimate residual bias per missingness pattern on held-out data; correct at inference time

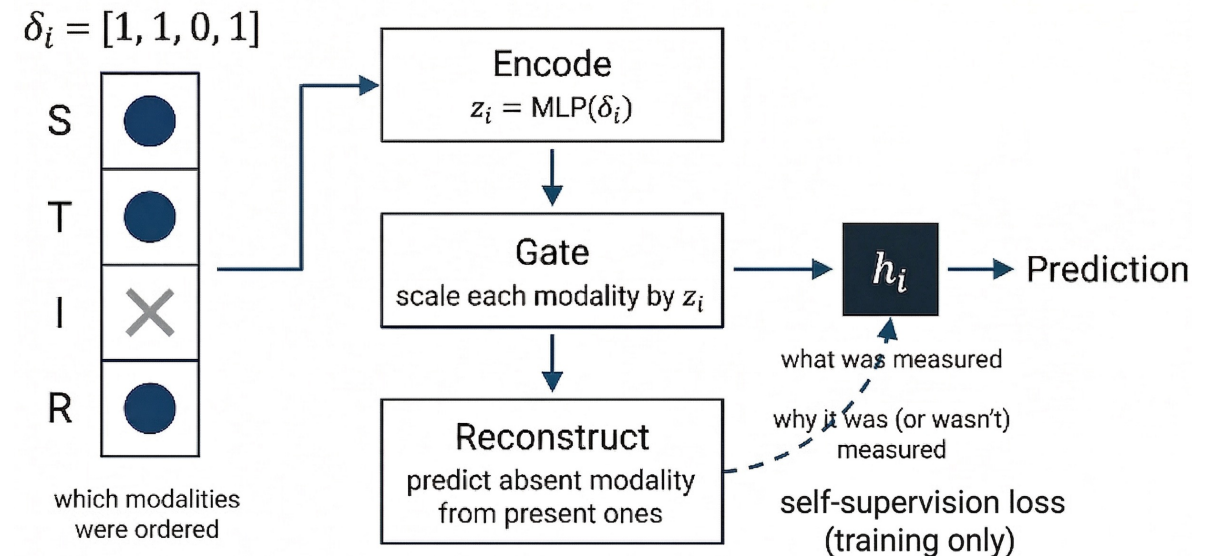


How Static Missingness Becomes Signal: The δ_i Pathway

The pattern of which modalities are present is itself a clinical signal — sicker patients get more tests.

- **Encode the pattern** — $\delta_i \in \{0,1\}^4$ is embedded directly: $z_i = \text{MLP}(\delta_i)$, giving the model an explicit representation of who was tested
- **Gate each modality** — each modality's contribution is weighted by z_i , so the representation knows why a modality is present or absent
- **Self-supervise completeness** — cross-modal reconstruction forces h_i to retain the information that missingness carries, beyond just the observed values

Result: h_i encodes not just what was measured, but what the measurement pattern reveals about the patient's underlying health state.



The Rectifier: Correcting Residual Missingness Bias

Even after learning a good representation, one causal path remains unblocked: the observation pattern δ_i directly affects outcomes beyond what h_i captures.

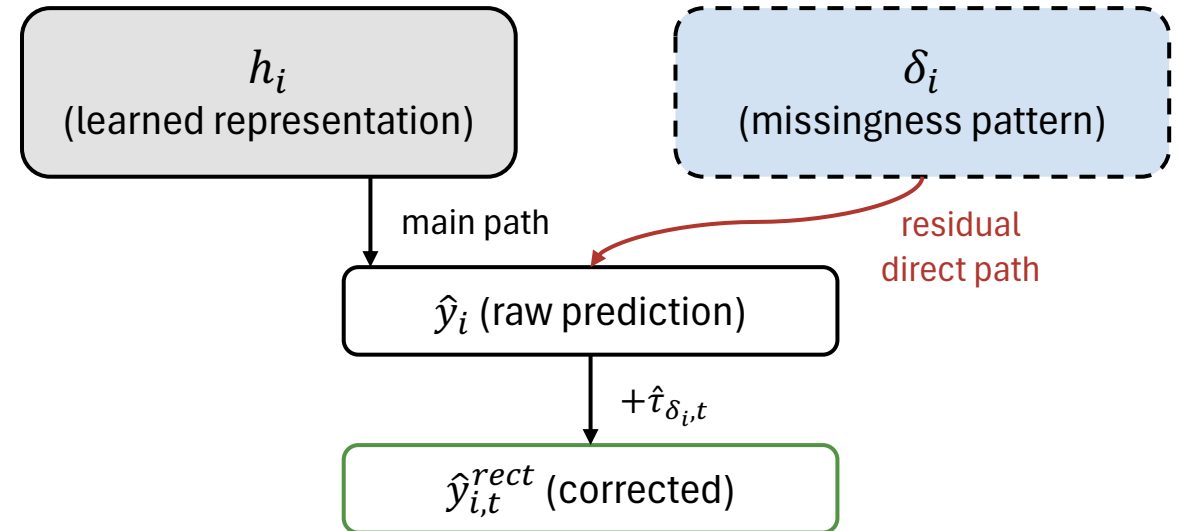
Example: ordering a chest X-ray is itself a clinical act — it may trigger further intervention, independent of what the image shows.

How it works (3 steps):

- Group patients by missingness pattern δ
- Estimate residual bias per pattern on held-out data
- Apply correction at inference if bias exceeds threshold κ

Key properties:

- ICU admission AUROC: +9.3% (MIMIC-IV ablation)
- Lightweight and overfitting-proof via cross-fitting



Instantiation II: Offline Decision-Making for Sepsis under Step-Level MNAR

Setting: Learn a treatment policy for sepsis management from historical ICU trajectories — no randomized trial, no online interaction.

Data (MIMIC-IV):

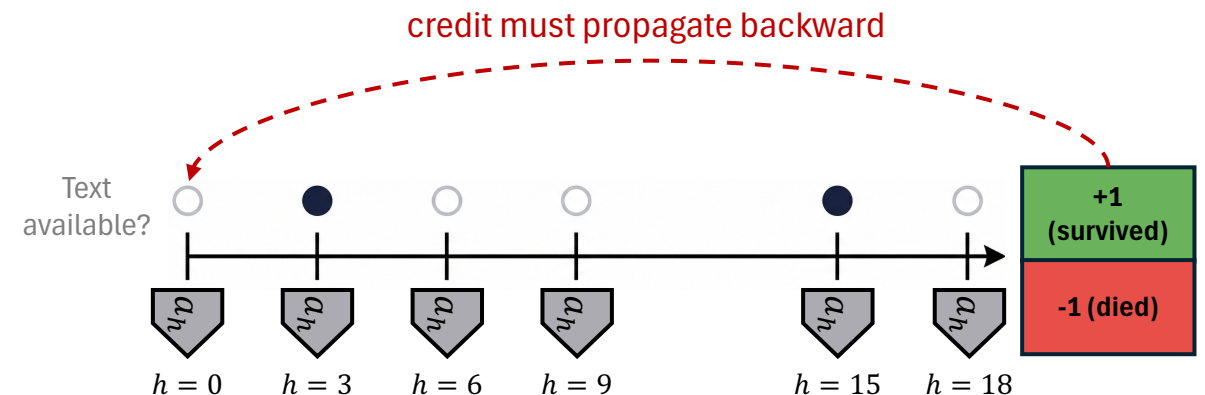
- 32,837 ICU stays · 28,419 unique patients · 11.8% in-hospital mortality
- 72-hour window → **H = 18 decision steps** at 4-hour intervals
- Text is step-level sparse: radiology available at only **83.6%** of steps; microbiology at **45.5%**

Action space: $3 \times 3 = 9$ discrete actions (IV fluids × vasopressors)

Reward: Sparse and terminal — +1 survival / -1 death; zero at all intermediate steps

Challenge:

Reward only arrives at step 18. But treatment decisions start at step 1. How does the model know which early action deserved credit for the final outcome?



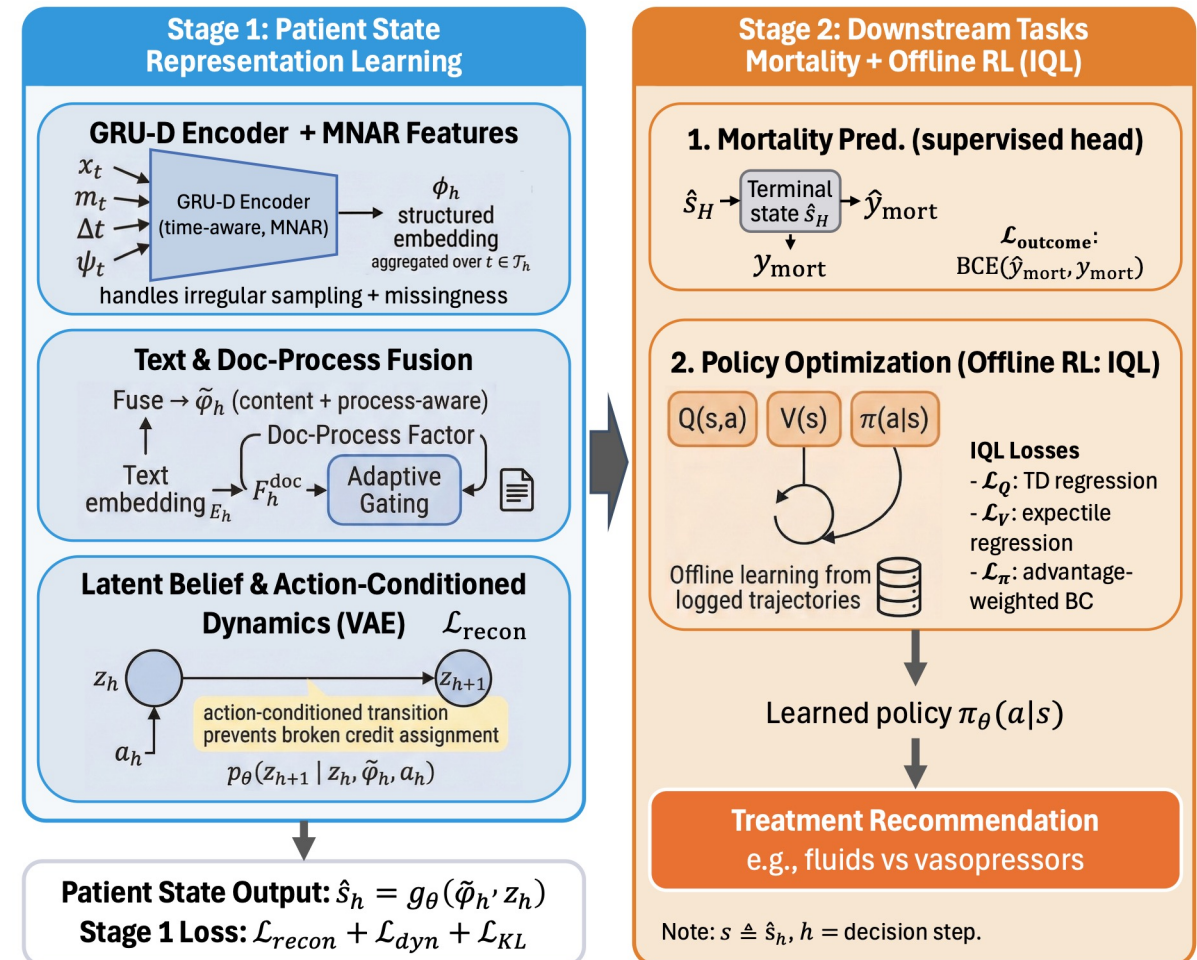
Instantiation II: MNAR-Aware State Learning for Offline Control

Stage 1 — Learn Decision-Step Patient States

- **Structured encoding (GRU-D):** Encodes not just values, but when and how often each variable was measured
- **Process-aware text fusion:** Stale or sparse documentation is discounted even when text is present
- **Action-conditioned dynamics:** Actions are wired into state transitions — enabling credit to flow backward to early decisions

Stage 2 — Optimize an Offline Policy

- Learns value functions from historical data without querying actions outside the dataset → outputs $\pi(a|s)$



How Temporal Missingness Becomes Signal: The $(m_t, \Delta t, \xi_h)$ Pathway

At each decision step, how a patient is monitored reveals as much as what is measured.

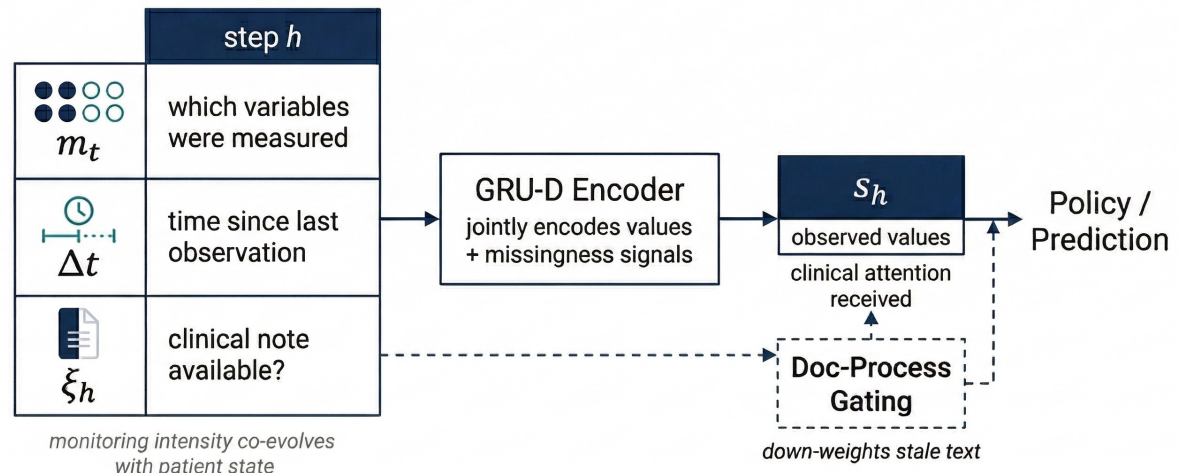
- **m_t (observation mask)** — which variables were measured at this step; sparse monitoring signals stability
- **Δt (time since last observation)** — longer gaps indicate the clinician judged the patient stable enough to skip
- **ξ_h (text availability)** — whether clinical notes exist at this step; absence is itself informative

GRU-D encodes all three jointly with the observed values — monitoring intensity co-evolves with patient state.

Doc-Process Gating: stale or sparse documentation is down-weighted at inference, so the model is not misled by the timing of text.

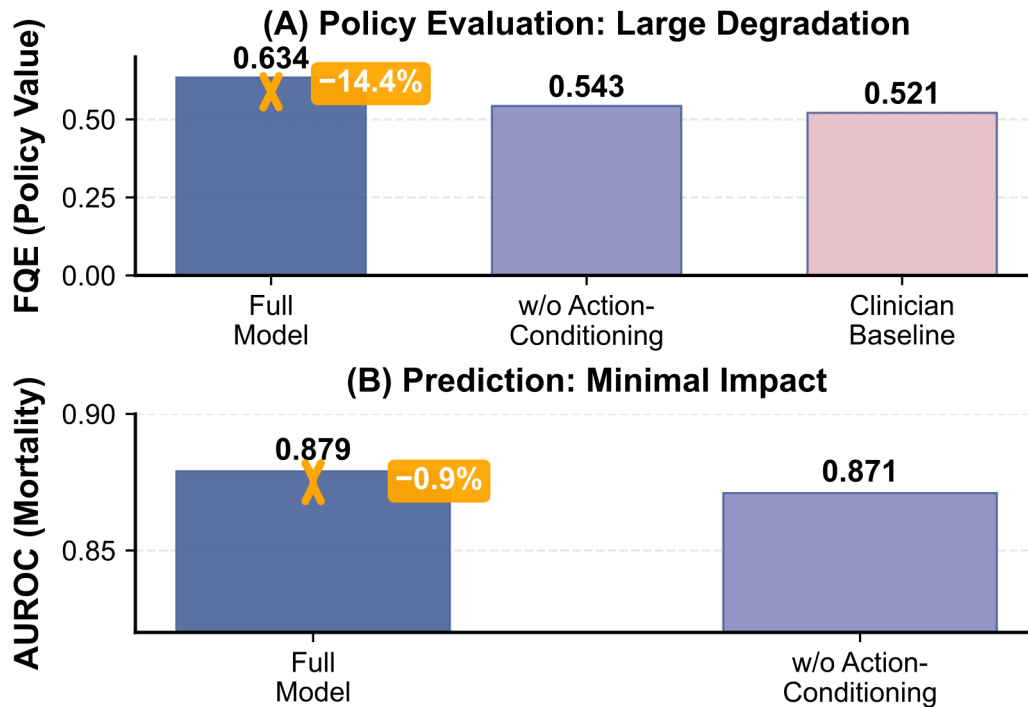
Result: s_h encodes not just vitals and labs, but the full clinical attention the patient received.

At each step h , three signals



Why Action-Conditioning Is Non-Negotiable: The RB Dissociation

The experiment: Remove action-conditioning from latent dynamics. What breaks?



Prediction barely changes. Policy collapses.

Why? Without action-conditioning, the reward gradient cannot reach early actions — credit assignment is severed by design.

Action Sensitivity (ActSens) confirms:

- Without action-conditioning: 0.023 (near zero)
- With action-conditioning: 0.847

Good Prediction ≠ Good Policy. This is not an engineering quirk — it is a structural property.

Results and Takeaways

From modeling ideas to empirical evidence

Results I: Static Prediction under MMNAR

Our method outperforms all 13 baselines on both MIMIC-IV and eICU.

Task	Best Baseline	Ours	Gain
ICU Admission (MIMIC-IV)	0.869 (DrFuse)	0.982	+13.0%
30-Day Readmission (MIMIC-IV)	0.799 (MUSE+)	0.866	+8.4%
In-Hospital Mortality (MIMIC-IV)	0.905 (MUSE+)	0.947	+4.6%

Some insights:

- **Robustness under distribution shift:** Under severe missingness shift ($KL = 1.0$), the AUROC gap for readmission widens from **+6.7%** to **+12.5%** — MMNAR-aware models become more advantageous when patterns shift.
- **It means** if the previous best model caught 87 out of 100 ICU admissions, our model catches 98.

Results II: Offline Decision-Making under Dynamic MNAR

Our policy outperforms clinician behavior and all RL baselines on both datasets.

Method	MIMIC-IV FQE	vs. Clinician	eICU FQE	vs. Clinician
Clinician (BC)	0.521	—	0.534	—
CQL	0.418	−19.8%	0.408	—
Tabular Q (AI Clinician)	0.491	−5.8%	0.478	—
Ours (IQL)	0.634	+21.7%	0.604	+13.1%

Outperforms AI Clinician by +29.1%, CQL by +51.7%

All four OPE estimators (FQE, WIS, PDIS, DR) confirm improvement; even the most conservative lower bound (WIS: 0.571) exceeds the clinician baseline (0.521)

Results II: Offline Decision-Making under Dynamic MNAR

Gains concentrate where it matters most — the sickest patients:

SOFA Severity	Clinician FQE	Ours FQE	Gain
Low (0–5)	0.684	0.756	+10.5%
Medium (6–10)	0.423	0.548	+29.6%
High (>10)	0.187	0.319	+70.6%

The AI helps most where clinicians struggle most — the most critically ill patients in the ICU.

Robustness and Cross-Institutional Generalization

Part 1 — Robustness to Missingness Pattern Shift (Static Setting)

Shift Severity	Ours	MUSE+	Gap
None (original)	0.866	0.799	+6.7%
Mild (KL = 0.2)	0.854	0.771	+8.3%
Moderate (KL = 0.5)	0.838	0.734	+10.4%
Severe (KL = 1.0)	0.812	0.687	+12.5%

Part 2 — Cross-Institutional Generalization (Dynamic Setting)

Protocol	Train → Test	FQE	vs. Clinician
In-distribution	MIMIC-IV → MIMIC-IV	0.634	+21.7%
Zero-shot transfer	MIMIC-IV → eICU	0.568	+6.4%
Fine-tuned transfer	MIMIC-IV + eICU FT → eICU	0.594	+11.2%

3 Practical Takeaways for Clinical AI Developers

Construct MNAR features explicitly

- Encode missingness as signal, not noise
- Removing MNAR features: FQE $\downarrow$ 13.4%, AUROC $\downarrow$ 3.2%

Apply the diagnostic atlas before deployment

- ECE elevated $\rightarrow$ Rectifier
- High Δ_{dissoc} + low ActSens $\rightarrow$ action-conditioned dynamics

Distinguish prediction objectives from decision-support objectives

- Good AUROC $\neq$ good policy
- If decision support is the goal: use FQE, not just AUROC

Conclusion

From specific methods to broader implications

Contributions at a Glance



1. Unified Cross-Scale MNAR Framework. Formalized patient-level modality assignment and step-level monitoring intensity as explicit causal variables within a structural causal model.



2. Instantiation I — Static Multimodal Prediction. Missingness-aware fusion + cross-fitted rectifier → AUROC gains of **+4.6% to +13.0%** over 13 baselines (MIMIC-IV); **+0.5% to +13.7%** on eICU.



3. Instantiation II — Dynamic Sequential Decision-Making. MNAR-aware encoder + action-conditioned latent dynamics + IQL → **+21.7%** over clinician behavior (MIMIC-IV); **+70.6%** for high-acuity patients (SOFA > 10).



4. MNAR Error Taxonomy & Diagnostic Atlas. Three failure regimes mapped to observable diagnostic signals and targeted interventions — enabling prospective deployment monitoring.

Future Directions



1. Sharper Causal Identification. Current framework corrects for $\delta \rightarrow y$ but does not identify the mechanism. Instrumental variable methods could enable counterfactual reasoning about the observation process itself.



2. Active Observation Strategies. Move from passively handling missingness to learning which measurements to acquire at each step — jointly optimizing observation cost against treatment benefit.



3. Multi-Site Federated Learning & Prospective Trials. Zero-shot transfer recovers only 72–81% of in-distribution performance. Federated learning + clinician-in-the-loop trials are needed to close the gap between OPE estimates and real-world impact.

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- Thank you for 3 years of guidance, challenge, and encouragement.

Names listed alphabetically within each category.

Thank You

"The incompleteness of clinical data is not merely a technical inconvenience to be overcome before the real modeling can begin.

It is a reflection of the human process through which knowledge about patients is gathered, filtered, and recorded — a process that is itself a rich source of signal about patient health and clinical priorities."

Models that model missingness outperform models that merely tolerate it.

Questions & Discussion

Thank you for listening!